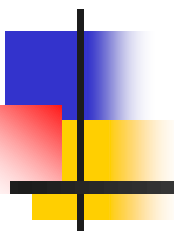


# Dimensional Similarity in Human Perception of Slope for Networked Virtual Haptic Environments



Trevor C. Amedayenou<sup>1</sup>, Yutaka Ishibashi<sup>1</sup>,  
Pingguo Huang<sup>2</sup>, Yuichiro Tateiwa<sup>1</sup>

<sup>1</sup>Nagoya Institute of Technology, Japan

<sup>2</sup>Gifu Shotoku Gakuen University, Japan

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# Background

## Networked virtual environments with haptics

We can perceive the features of the shape, softness, and weight of an object through a haptic interface device by touching/holding the object.

When haptic information is transmitted over a network such as the Internet, which does not guarantee QoS (Quality of Service )

**QoE (Quality of Experience)  
deterioration**

*Network delay, delay jitter,  
and packet loss*

**For effective QoS control, we need to investigate human perception of object features such as the shape, surface smoothness, softness, and weight of the object.**

**QoS control**

# Previous Work (1/3)

- The inter-stream synchronization control between audio and haptic media streams is proposed <sup>\*1</sup>, as QoS control taking advantage of human perception
- Two perception ranges of inter-stream synchronization error are introduced

- 
- **Imperceptible range:** Users cannot perceive the error
  - **Allowable range:** Users feel that the error is allowable

## Problem

➤ The ranges are not clarified so far.

\*1 Y. Ishibashi *et al.*, ACM Multimedia, pp. 604-611, Oct. 2004.



## Previous Work (2/3)

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Carried out QoE assessment of human angle perception\*<sup>2</sup> for networked virtual environments.



Clarified the **imperceptible range**, **allowable range**, and **perceptible range** (i.e., all the users can perceive the angle difference) of angle perception.

### Problem

The human perception of other features such as shape and surface smoothness has not sufficiently been clarified so far.

\*<sup>2</sup> J. Ma *et al.*, CECIT, Dec. 2021.



## Previous Work (3/3)

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**Investigate the human slope perception on the  $y$ -axis<sup>\*3</sup> by touching the surface of each slope with a haptic interface device by QoE assessment instead of angles<sup>\*2</sup> in the object perception system.**



**Demonstrate that the human perception largely depends on the angle of the standard slope and the slope difference**

### Problem

➤ **The human perception on the  $x$ - and  $z$ -axes is not clarified.**

<sup>\*3</sup> A. T. Christian *et al.*, WSCE, pp. 6-10, Sep. 2022.



# Purpose

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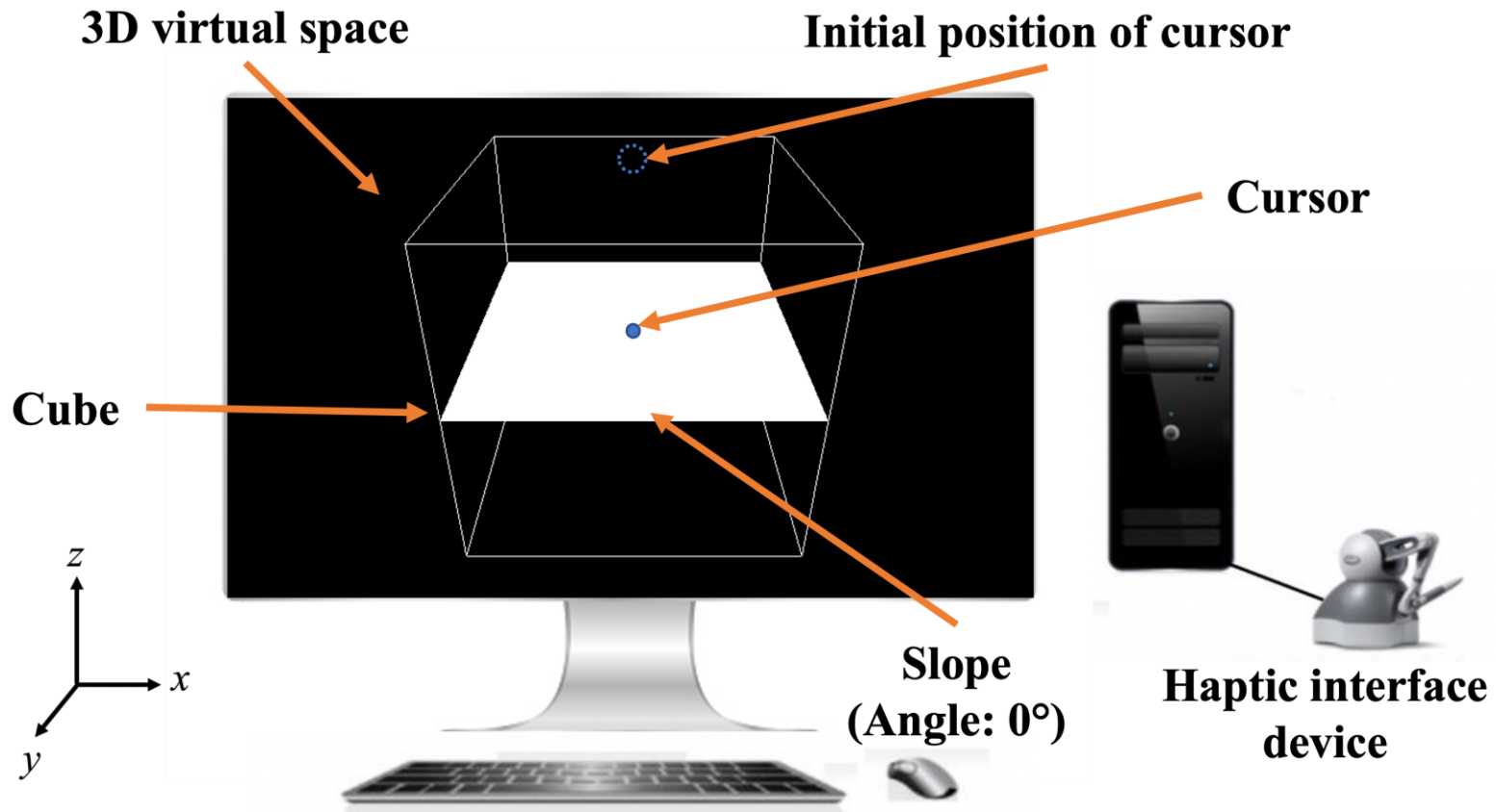
## This work

- **We investigate the human slope perception on the  $x$ - and  $z$ -axes by QoE assessment.**
- **We make a comparison with our previous results<sup>\*3</sup> on the  $y$ -axis.**

\*3 A. T. Christian *et al.*, WSCE, pp. 6-10, Sep. 2022.

# Object Perception System (1/3)

- **Visible mode:** User can look at slopes.

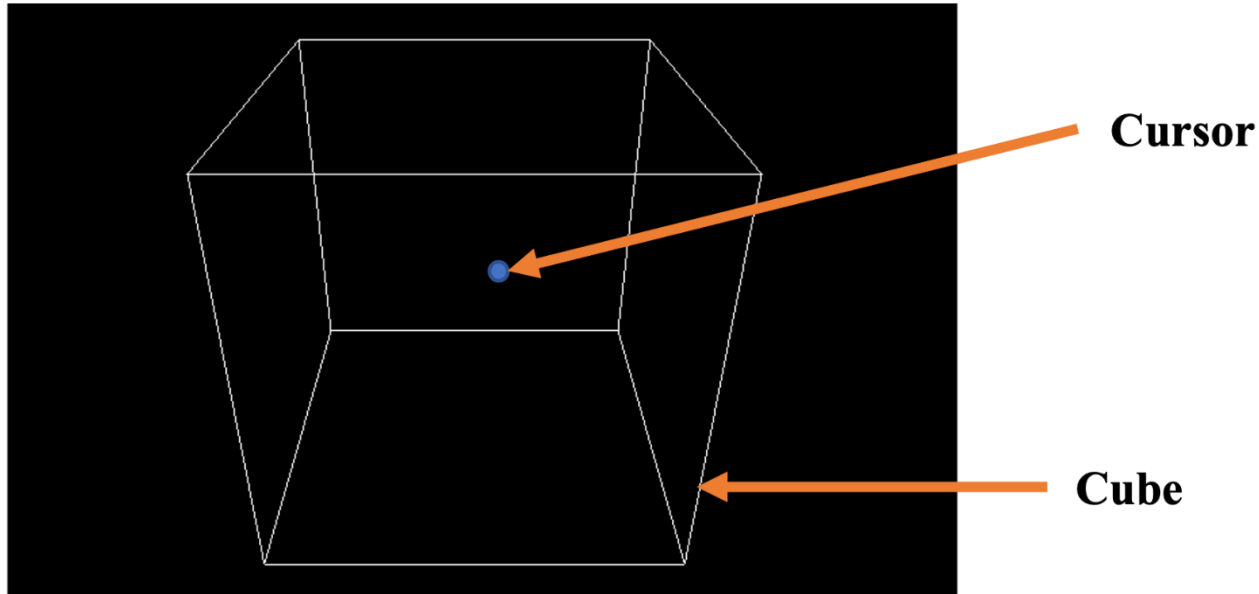


- **Invisible mode:** User cannot look at slopes.



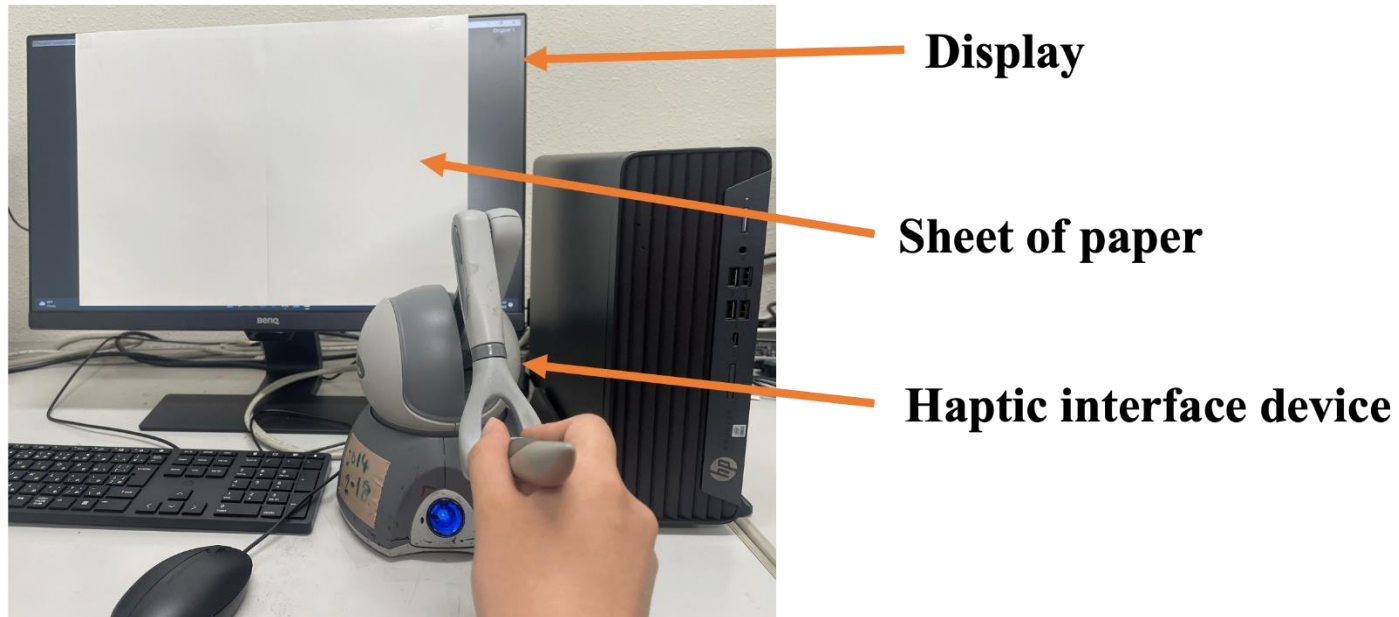
# Object Perception System (2/3)

- **Invisible mode**



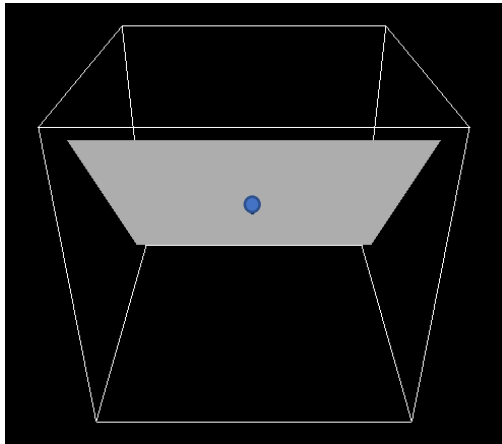
# Object Perception System (3/3)

- **Invisible mode (covered by a sheet of paper)**

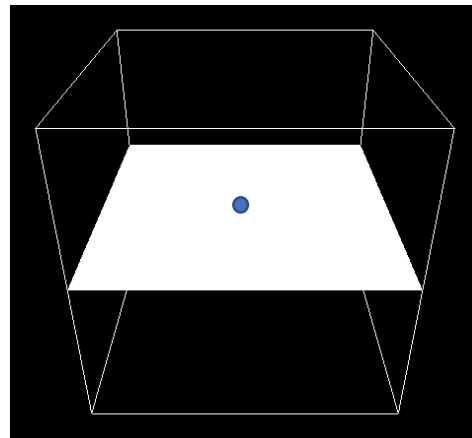
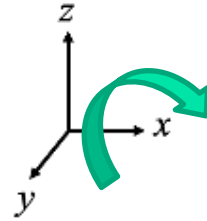


# Slopes as Objects (1/2)

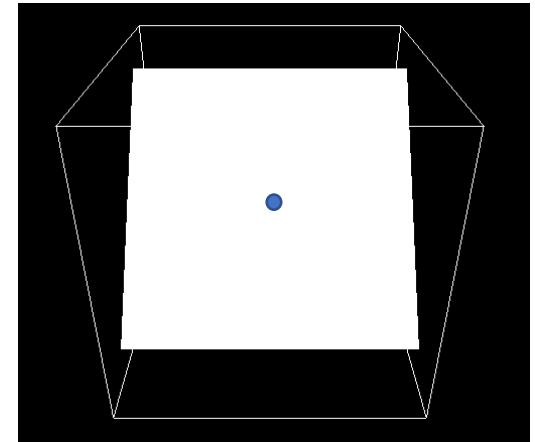
- **x-axis**



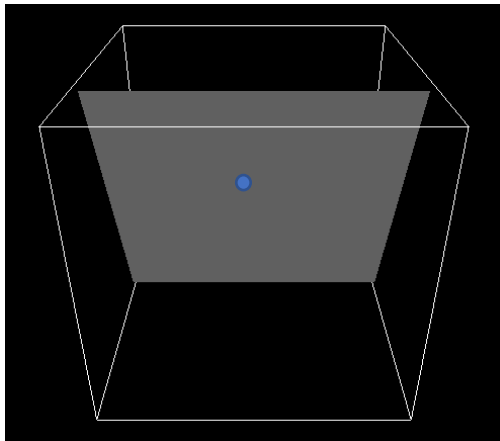
**(a) Angle:  $-50^\circ$**



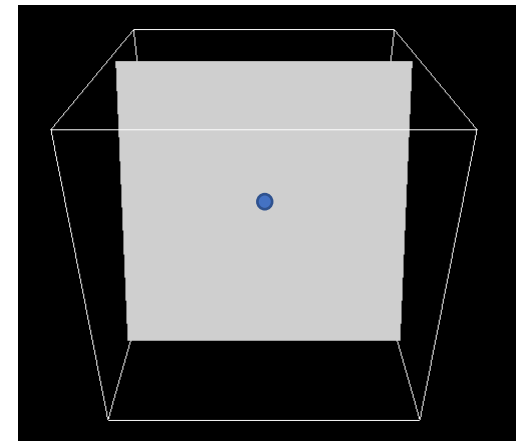
**(c) Angle:  $0^\circ$**



**(b) Angle:  $50^\circ$**



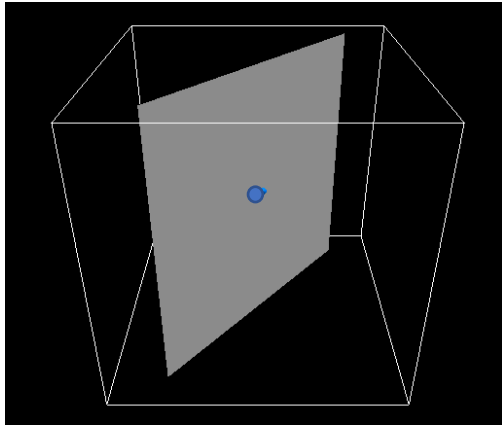
**(d) Angle:  $-70^\circ$**



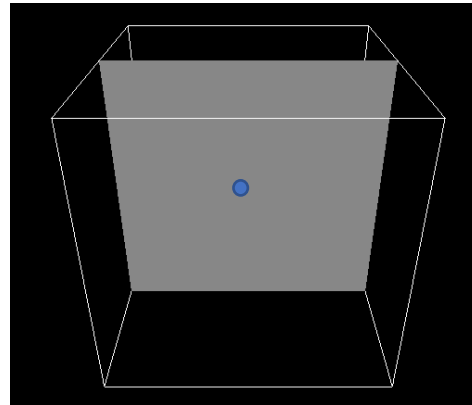
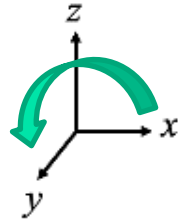
**(e) Angle:  $70^\circ$**

# Slopes as Objects (2/2)

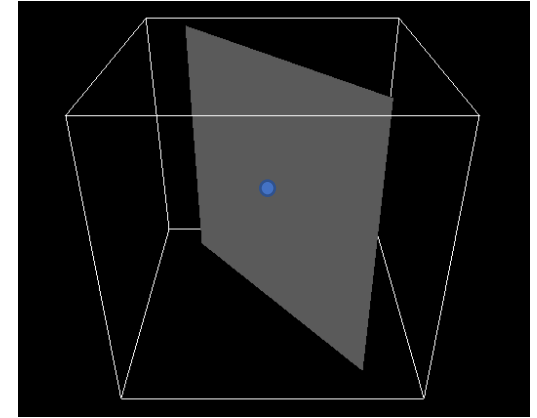
- z-axis



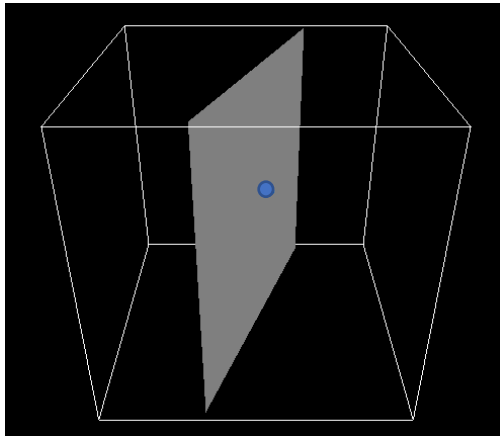
(a) Angle:  $-50^\circ$



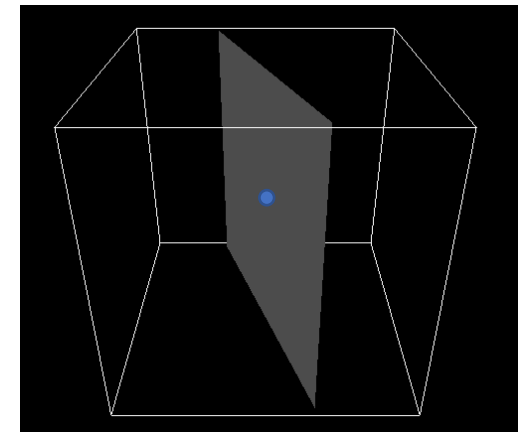
(c) Angle:  $0^\circ$



(b) Angle:  $50^\circ$



(d) Angle:  $-70^\circ$



(e) Angle:  $70^\circ$

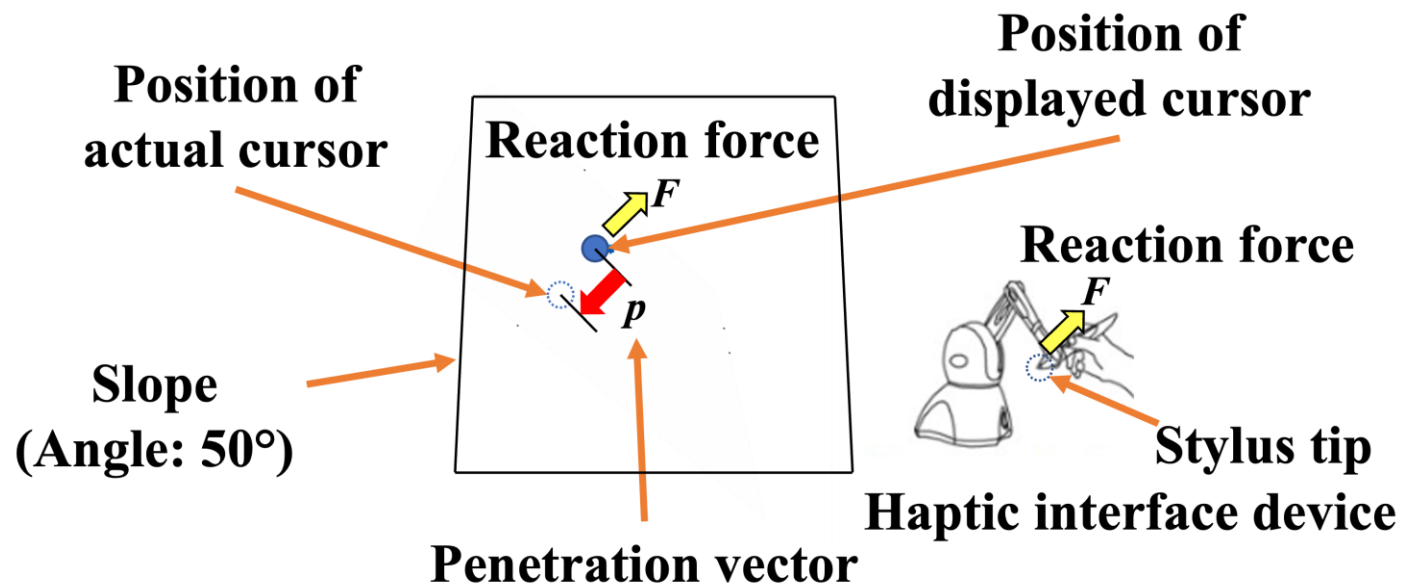
# Calculation of Reaction Force (1/2)

The reaction force  $F$  is calculated by the spring-damper model.

$$F = -K_s p$$

$K_s$ : Spring (or elasticity) coefficient

$p$ : Vector from the center of the displayed cursor on the slope surface to the center of the actual cursor





## Calculation of Reaction Force (2/2)

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- In networked virtual environments, as the network delay increases,  $|p|$  becomes larger \*4.
- If the network delay fluctuates when we are touching a slope, we may not be able to accurately feel the slope angle accurately.



**It is important to investigate the human perception of slopes.**

\*4 M. Fujimoto *et al.*, IEICE Trans. Commun., pp. 589-592, Apr. 2004.



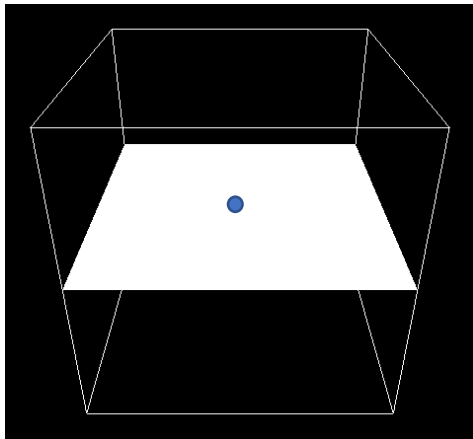
# Assessment Method (1/3)

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- We handled five slopes (called the *standard slopes* ) with rotation angles of  $0^\circ$  ,  $\pm 50^\circ$  , and  $\pm 70^\circ$  on the  $x$ - and  $z$ -axes
- **Stimuli**: Comparison between each standard slope and other slopes (called the *test slopes*). Pairs of the standard and test slopes were presented in random order for each subject.
- Before the assessment, each subject practiced touching the standard and test slopes in the visible mode.

# Assessment Method (2/3)

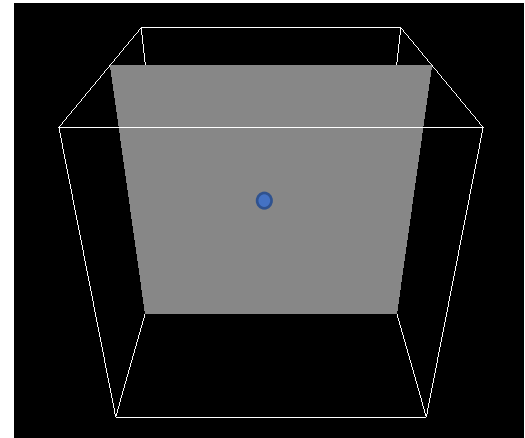
- **x-axis**



Angle: 0°



- **z-axis**



Angle: 0°

- **x-axis:** Lowering the cursor from the top
- **z-axis:** Moving the cursor in from back direction





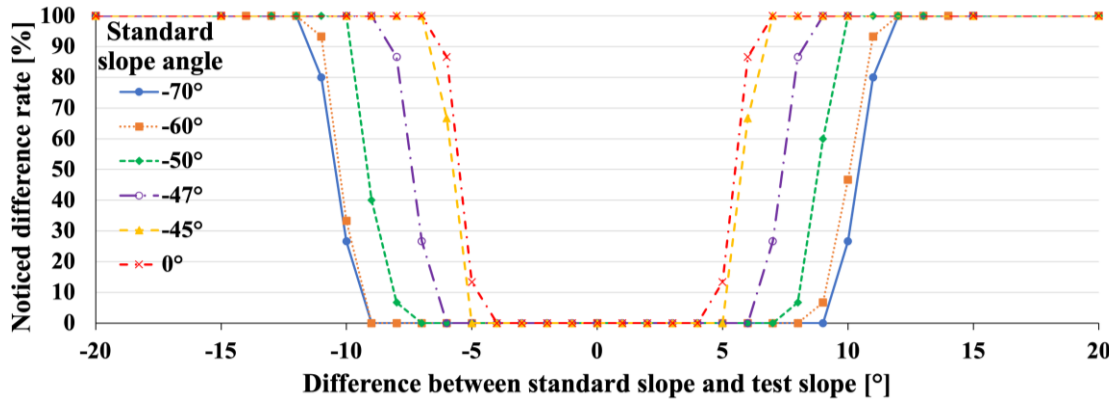
# Assessment Method (3/3)

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- **The assessment is carried out in invisible mode. Also, the cursor is hidden by covering the display of the PC with a sheet of paper.**
- **Work: Trace the surface of each slope from right to left and from front to back about 4 times each direction for 10 seconds.**
- **Judgment: Answer whether the difference in angle between the standard and test slopes is noticeable or not.**
- **Subjects: 15 (13 men and 2 women)**

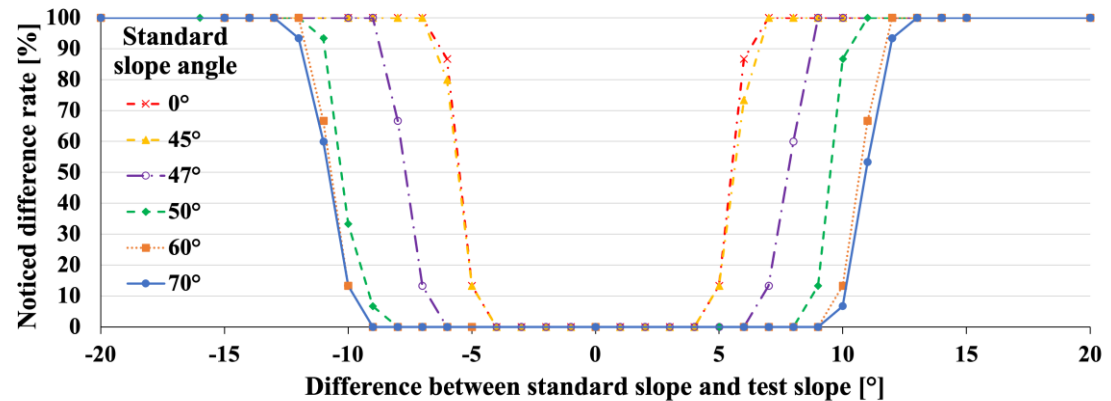
# Assessment Results (1/2)

• **y-axis**



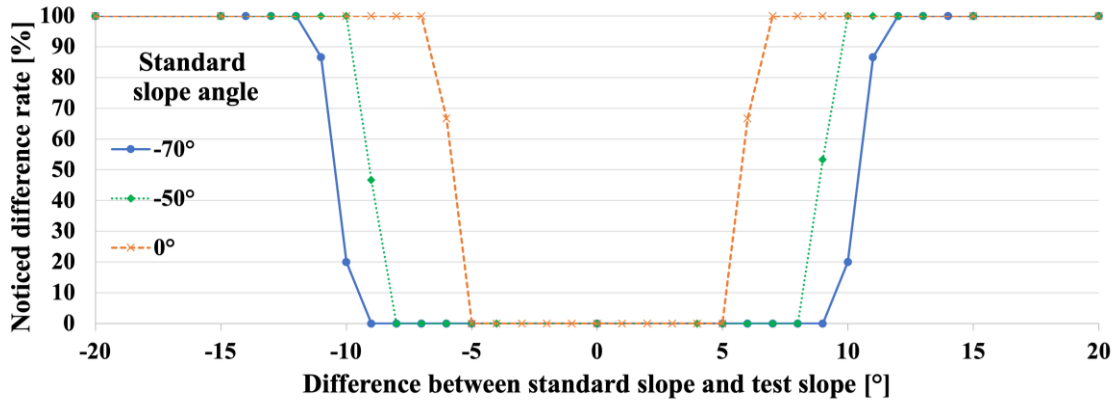
Noticed difference rate versus difference in angle between standard slope and test slope (angle of standard slope from -70° to 0°).

Noticed difference rate versus difference in angle between standard slope and test slope (angle of standard slope from 0° to 70°).



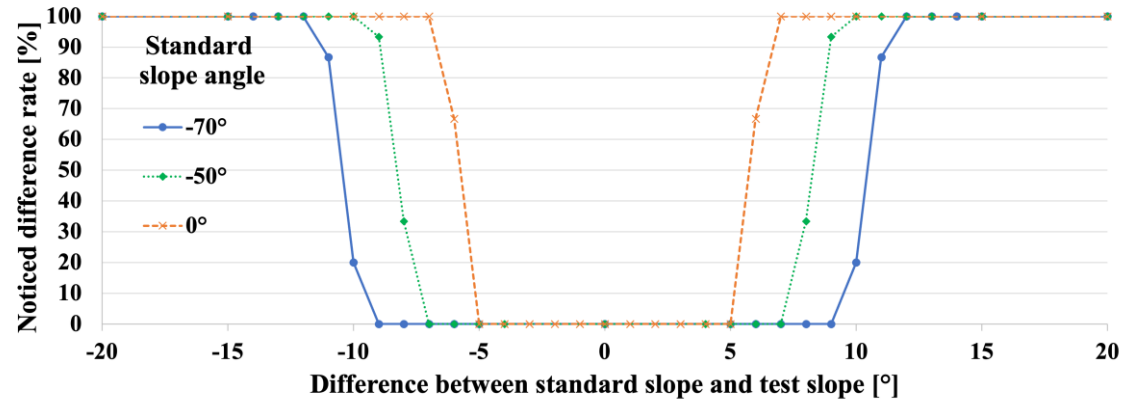
**Noticed difference rate:** Percentage of subjects who perceived the difference.

# Assessment Results (2/2)



Noticed difference rate versus difference in angle between standard slope and test slope (angle of standard slope on the **x-axis**: from  $-70^\circ$  to  $0^\circ$  ).

Noticed difference rate versus difference in angle between standard slope and test slope (angle of standard slope on the **z-axis**: from  $-70^\circ$  to  $0^\circ$  ).



**Noticed difference rate:** Percentage of subjects who perceived the difference.



# Conclusion

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- We examined the dimensional similarity in human slope perception with haptic sense for networked virtual environments by QoE assessment.
- We handled slopes on the  $x$ - and  $z$ -axes and made a comparison with those on the  $y$ -axis.



- We found that there is dimensional similarity in human slope perception among the three axes.



# Future Work

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- **Discuss the assessment results in relation to the Weber's law** (*"The law states that the change in a stimulus that will be just noticeable is a constant ratio of the original stimulus."* \*5).
- **Study QoS control by taking account of human perception.**

\*5 Britannica - Weber's law. Retrieved Feb. 17, 2023 from <https://www.britannica.com/science/Webers-law>.